Towards Safe AI for Automated Driving

Fabian Hüger, Volkswagen & CARIAD EDCC 2021, September 16, 2021

The results, opinions and conclusions expressed in this publication are not necessarily those of Volkswagen Aktiengesellschaft.

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1. Introduction – CARIAD

We deliver Volkswagen's answer to the digitalization of mobility



Our Solutions

Our solutions are structured in technology domains and product enablers



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Automated Driving and Al

Processing chain of autonomous driving & the use of Al along



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Arguing Safety in Automated Driving Systems Al goes safety critical

CENTRAL CHALLENGE

SAFETY (FuSa + SOTIF)

<u>Central Challenge</u> in bringing highly automated driving on the road.

Argument on safe functioning needed to allow for acceptance & road permission





COMPLEXITY DRIVERS

Mere driving will not suffice to plausibilize

safety – particularly challenging with respect to software updates over time. "Black-Box" approach seems impracticable

Handling complexity of the driving environment – open world, unknown unknowns, etc.

Need for continual safety monitoring & assurance – continuous monitoring



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Arguing Safety in Automated Driving Systems Standardization Activities

EXISTING STANDARDS ADDITIONAL NORMS & DOCUMENTS WORK IN PROGRESS ISO Activities UL4600 S() | | | =ASAM working groups ISO 21448 **ISO 26262** Safety alongside Approaching standards for • E/E failures Behavioral safety development process - Leveldependability of AI: (describing performance Classification in ASII -Levels 4 specific, more Al details limitations and triggering No defined ML-specifics (in conditions alongside • Focus within the development ISO/IEC JTC1 SC42 activities discussion for the 3rd mitigation techniques) process - reporting on design (ISO TR5469, ISO/IEC TR edition) decisions with respect to raise 24029) • Highly relevant for non-fully resulting safety is key • ASAM working groups specified perception Consequently: yielding need systems for which DNNs • ISO TR 4804 for a strong traceability of seem to be standard ISO TS 5083 performance and ٠ safety evidence to ISO NWIP Road Vehicles: development decisions. Safety & Al

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KI-Absicherung Project & Approach

ABSICHERUNG

Safe AI for Automated Driving

www.ki-absicherung-projekt.de 🈏 @KI_Familie 🖬 KI Familie

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KIABSICHER UNG

Safe AI for Automated Driving

Pedestrian detection

Challenge



Industry consensus (Safe AI): Methodology for joint safety argumentation



Our Approach: Specification











Our Approach: Al Function Pedestrian detection





Semantic Segmentation



2D Bounding Box Detection



Instance Segmentation



3D Bounding Box Detection





Our Approach: Synthetic Data and ML-Lifecycle













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Our Approach: ML-Lifecycle-Validation data







Continuous process for identification, specification and generation of synthetic data







M. Mock et al.: An Integrated Approach to a Safety Argumentation for AI-based Perception Functions in Automated Driving, WAISE @SafeCOMP 2021)





Our Approach: DNN-specific Safety Concerns (1/2)



We define **DNN-specific Safety Concerns (SCs)** as underlying issues of DNN-based perception which may negatively affect the safety of a system.



FI-1	INSUFFICIENT GENERALIZATION CAPABILITY Wrong outputs by an AI-based function that was trained on a limited database. Erroneous input to output mapping or wrong approximation.	SC-2.2	INADEQUATE SEPARATION OF TEST AND TRAINING DATA Test data might be correlated to training data which might induce overfitting on test data.	
SC-1.1	UNRELIABLE CONFIDENCE INFORMATION DNNs tend to be overconfident in their predictions under certain conditions or in general outputting unreliable confidence information.	SC-2.3	DEPENDENCE ON LABELLING QUALITY Labelling quality can directly affect the resulting model performance. Moreover, due to missing labelling quality, evaluation results might be misleading.	Based on: O. Willers, S. Sudholt, S. Raafatnia, S. Abrecht: Safety Concerns and Mitigation Approaches Regarding the Us
SC-1.2	BRITTLENESS OF DNNS Non-robustness against common perturbations such as noise or certain weather conditions as well as targeted perturbations known as adversarial examples	SC-2.3.1	MISSING LABEL DETAILS OR META-LABELS Missing meta-labels or label details possibly leads to improper data selection or insufficient training objectives.	of Deep Learning in Safety- Critical Perception Tasks T. Sämann, P.Schlicht, F. Hüger: Strategy to Increase the Safety of a DNN-based Perception for HAD Systems G. Schwalbe, B. Knie, T. Sämann. T. Dobberohul, L.
SC-1.2.1	LACK OF TEMPORAL STABILITY Detection results rapidly changing in time whereas little change occurs in the ground truth	SC-2.4	SPECIFICATION OF THE ODD An incomplete or incorrect ODD specification leads to incomplete data records for training and testing.	Gauerhof, S., V. Rocco: Structuring the Safety Argumentation for Deep Neural Network Based Perception in Automotive Applications
SC-1.3	INCOMPREHENSIBLE BEHAVIOUR Inability to explain exactly how DNNs come to a decision.	SC-2.5	DISTRIBUTIONAL SHIFT OVER TIME A DNN is trained and tested at a certain point in time. Changes will occur naturally and therefore can potentially harm the performance of DNNs.	Functional Insufficiencies
SC-1.4	INSUFFICIENT PLAUSIBILITY Al based functions usually lack basic plausibility checks, which are intended to identify detections of the perception	SC-2.6	UNKNOWN BEHAVIOUR IN RARE CRITICAL SITUATIONS The long tail problem describes the fact that there exists an enormous amount of possibly safety-critical street scenes	DNN- characteristics- related concerns
SC-2.1	function that violate physical laws. DATA DISTRIBUTION IS NOT A GOOD APPROXIMATION OF REAL	SC-3.1	that have a low occurrence probability. SAFETY-AWARE METRICS	Data-related concerns
	WORLD The distribution of data used in the development should be a valid approximation of the ODD in the real world.		Some state-of-the-art metrics only evaluate the average performance of DNNs. Safety-aware metrics are required to sophistically evaluate the performance of DNNs.	Metric-related concerns

DNN-specific Safety Concerns 21

Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns" via MC dropout

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Uncertainties for Location and Size



Approximating COV($(x_i, y_i)_{i \in \text{samples}}$) using Monte Carlo Dropout (x, y): position) 0 30 60 90 120 130

<image><image><text><image><image>

 $\begin{aligned} & \text{Avg}_{i \in \text{object}}(\text{Entropy}(\text{Avg}_{s \in \text{sample}} \text{ softmax}_{i,s})) \\ & \text{using Monte Carlo Dropout} \end{aligned}$

 Objects:
 average bounding box over sampling from Bounding Box Detection

 Classification:
 average softmax over sampling from Semantic Segmentation

Adressed Safety Concern: Unreliable Confidence via MC dropout

DNN-specific safety concern:

Unreliable Confidence
 Information of DNNs

Method:

- Assessment of uncertainty: Stochastic evaluation of a multitude of model variations (Monte Carlo Dropout)
- Usage at design-time or run-time

Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns"

Adressed Safety Concern: Brittleness of DNNs

- Adressing "Brittleness of DNNs" (Example)
 - Requirement: Robustness = Performance even under reasonable perturbations (gained from ODD definition, data analysis and sensor specs)
 - Metric: Performance under corruption
 - Methods (e.g.)
 - Augmentation Training (AugMix)
 - From a Fourier-Domain Perspective on Adversarial Examples to a Wiener Filter Defense for Semantic Segmentation
 - **Evidence**: Effectiveness of measure via metric





Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns" via AugMix

Adressed Safety Concern: Brittleness of DNNs Corruption Robustness



AugMix: A Simple Data Processing Method to Improve Robustness and Uncertainty, D. Hendrycks et al, https://arxiv.org/abs/1912.02781

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Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns" via AugMix

Adressed Safety Concern: Brittleness of DNNs Corruption Robustness

Augmented Image

Baseline Segmentation

Defended Segmentation



Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns"

Adressed Safety Concern: Brittleness of DNNs Adversarial Attacks

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From a Fourier-Domain Perspective on Adversarial Examples to a Wiener Filter Defense for Semantic Segmentation, N. Kapoor et al. *https://arxiv.org/abs/2012.01558*

Our Approach: Identify, Measure and & Counteract "DNN-specific Safety Concerns" via Wiener Filters Adressed Safety Concern: Brittleness of DNNs Adversarial Attacks

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Wiener Filters (WF) as an online denoising module **Steps**:

- 1. Convert input image to DFT domain.
- 2. Apply pre-computed WF as a multiplicative filter.
- 3. Convert to spatial domain using IDFT.
- 4. Feed image to target DNN.



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Our Approach: Explore Mechanisms!

- Heatmap-based Attention Consistency Validation
- Mixture of Experts
- Domain Randomization in Optimized Dataset Selection
- MC Dropout
- Uncertainties For Anomaly Detection
- Hybrid Learning using Concept Enforcement
- Active Learning

...

- Adverserial Training
- Hybrid and robustness-focussed Compression

Approx 80 Mechanisms are developed and evaluated

Inspect, Understand, Overcome: A Survey of Practical Methods for Al Safety

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M. Mock et al.: An Integrated Approach to a Safety Argumentation for AI-based Perception Functions in Automated Driving, WAISE @SafeCOMP 2021)

Our Approach: Summary



Our Approach: Evidence Workstreams



Empowering experts from safety engineering and ML to produce measures and evidences



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Summary

Findings & Consequences

- Safe AI is a central challenge for highly automated driving
- KI-Absicherung provides an approach for Safe AI
- Approach may serve as template for the industry and beyond
- Deep integration of Al-specifics into development PMT is necessary (continuous assurance of Al)



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https://scholar.google.de/citations?user=ISPOi1UAAAAJ

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Thank you!



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